

Người soạn:

Nguyễn Nhật Quân

Nguyễn Thành Liêm

$$a) T_1[x[n]] = \sum_{k=0}^n x[k]$$

Unstable:

Choosing $n = \infty$, we obtain $\sum_{k=0}^{\infty} x[k] = \infty$

Thus, the system is unstable.

Causal:

The output depends only on the present input.

Linear:

We find the response of the system to two separate input signals $x_1[n]$ and $x_2[n]$. The result is

$$y_1 = \sum_{k=0}^n x_1[k]$$

$$y_2 = \sum_{k=0}^n x_2[k]$$

The output of the system to a linear combination of $x_1[n]$ and $x_2[n]$ is

$$y_3[n] = T[a_1 x_1[n] + a_2 x_2[n]] = \sum_{k=0}^n [a_1 x_1[k] + a_2 x_2[k]] = a_1 \sum_{k=0}^n x_1[k] + a_2 \sum_{k=0}^n x_2[k] \quad (1)$$

Finally, a linear combination of the two outputs in yields

$$a_1 y_1[n] + a_2 y_2[n] = a_1 \sum_{k=0}^n x_1[k] + a_2 \sum_{k=0}^n x_2[k] \quad (2)$$

By comparing (1) with (2), we conclude that the system is linear.

Time – Variant:

We have:

$$y[n - n_0] = \sum_{k=0}^{n-n_0} x[k - n_0] = \sum_{k=0}^n x[k - n_0] \quad (1)$$

$$T[x[n - n_0]] = \sum_{k=0}^n x[k - n_0] = \sum_{k=0}^n x[k - t_0] \quad (2)$$

By comparing (1) and (2), we obtain the system is time – variant.

$$b) T_2[x[n]] = \sum_{k=n-10}^{n+10} x[k]$$

Stable:

$$T_2[x[n]] = \left| \sum_{k=n-10}^{n+10} x[k] \right| \leq \sum_{k=n-10}^{n+10} |x[k]| \leq [n+10 - n-10 + 1]M \leq 21M$$

$$\lim_{n \rightarrow \infty} T_2[x[n]] = 21M < \infty$$

Thus, $T_2[x[n]]$ is stable.

Causal:

The output depends only on the present input, thus $T_2[x[n]]$ is causal.

Linear:

We find the response of the system to two separate input signals $x_1[n]$ and $x_2[n]$.

The result is

$$y_1 = \sum_{k=n-10}^{n+10} x_1[k]$$

$$y_2 = \sum_{k=n-10}^{n+10} x_2[k]$$

The output of the system to a linear combination of $x_1[n]$ and $x_2[n]$ is

$$y_3[n] = T[a_1 x_1[n] + a_2 x_2[n]] = \sum_{k=n-10}^{n+10} [a_1 x_1[k] + a_2 x_2[k]] = a_1 \sum_{k=n-10}^{n+10} x_1[k] + a_2 \sum_{k=n-10}^{n+10} x_2[k] \quad (1)$$

Finally, a linear combination of the two outputs in yields

$$a_1 y_1[n] + a_2 y_2[n] = a_1 \sum_{k=n-10}^{n+10} x_1[k] + a_2 \sum_{k=n-10}^{n+10} x_2[k] \quad (2)$$

By comparing (1) with (2), we conclude that the system is linear.

Time – Variant:

We have,

$$y[n-n_0] = \sum_{k=n-10-n_0}^{n+10-n_0} x[k-n_0] = \sum_{k=t-10}^{t+10} x[t] \quad (1)$$

$$T[x[n-n_0]] = \sum_{k=n-10}^{n+10} x[k-n_0] = \sum_{k=0}^t x[t-t_0] \quad (2)$$

From (1) and (2), we have the system is time – variant.

c) $T_3[x[n]] = x[-n]$

Unstable:

We have,

$$|T_3[x[n]]| = |x[-n]| \leq x[|-n|+1] \leq |-n|M$$

On the other hand,

$$\lim_{n \rightarrow \infty} |-n|+1 = \infty$$

Thus, we conclude the system is unstable.

Noncausal:

For example 1, $n = -1$, which yields $y[-1] = x[1]$. Thus the output at $n = -1$ depends on the input at $n = 1$, which is two unit of time into the future.

Linear: We find the response of the system to two separate input signals $x_1[n]$ and $x_2[n]$.

The result is

$$y_1 = x_1[-n]$$

$$y_2 = x_2[n]$$

The output of the system to a linear combination of $x_1[n]$ and $x_2[n]$ is

$$y_3[n] = T[a_1x_1[n] + a_2x_2[n]] = a_1x_1[-n] + a_2x_2[-n]$$

Finally, a linear combination of the two outputs in yields

$$a_1y_1[n] + a_2y_2[n] = a_1x_1[-n] + a_2x_2[-n]$$

Time – Invariant:

We have,

$$y[n-n_0] = x[-n+n_0] \quad (1)$$

$$T_3[x[n-n_0]] = x[-n-n_0] \quad (2)$$

Comparing (1) and (2), we conclude the system is time – variant.